


# QUICK START GUIDE

# NEXUS REBEL JZ OVERVIEW

**What is a Nexus Rebel JZ Engine Control Unit?**

- A new generation engine management system designed to control Toyota JZ engines
- A wideband O2 controller
- A data logger
- A high speed Wi-Fi communications module
- All natively interconnected with each other
- All programmable with one single piece of software

The Nexus Rebel JZ ECU is one of Haltech's advanced engine control units in the Nexus range, offering additional functionality beyond simply controlling your Toyota JZ engine. It functions not only as an engine control unit but also as a wideband O2 controller, a data logger, and a Wi-Fi module, all integrated into a single unit. With its innovative and user-friendly technology, the Rebel JZ ECU sets a new standard in the market for Toyota JZ engine management. Paired with a Nexus Rebel JZ terminated harness, it provides a comprehensive range of performance and tuning capabilities for the following Toyota JZ engines:

- **1JZ-GTE Non-VVT-i**
- **2JZ-GTE Non-VVT-i**
- **1JZ-GE VVT-i**
- **2JZ-GE VVT-i**
- **1JZ-GTE VVT-i**
- **2JZ-GTE VVT-i**




**NEX-US** [noun]

– a connection or series of connections linking two or more things.

– a connected group or series

– the central or most important point or place

Scan this QR code to access more information about the Nexus Rebel JZ ECU



**What's in the box?**

- NEXUS Rebel JZ ECU
- 4AWG ring terminals, nuts and washers
- Terminal boots (Red & Black)
- Wi-Fi antenna RP-SMA 108mm
- Mounting bolts
- USB-C cable
- USB-C dust cap
- Bosch LSU 4.9 sensor
- Haltech air temp sensor (1/8 NPT)
- Bosch knock sensors and adapters
- Haltech 150 PSI oil pressure sensor, includes 1/8BSPT male to 1/8NPT female adapter
- Rebel JZ main terminated harness
- Alternator adapter harnesses
- Toyota R154 transmission sub harness
- Cable throttle adapter
- EV1 injector harness
- R35 Coil On Plug ignition harness



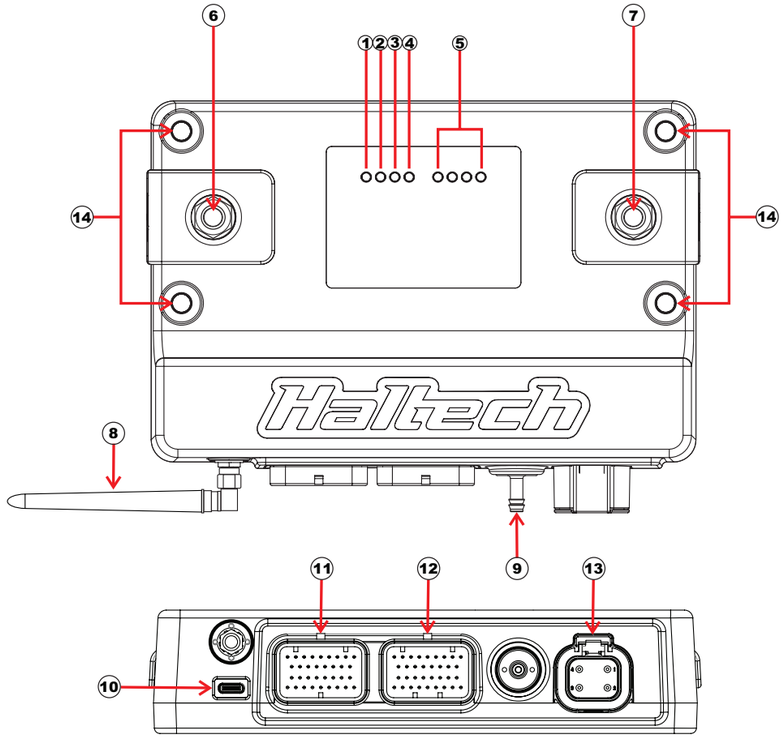

**Rebel JZ accessories**

These can be purchased separately or as part of a kit:

- xJZ DBW Sub-harness: HT-186162
- i6 Sumitomo (Denso) Primary Injector Harness: HT-186010
- i6 GT150 (USCAR EV6) Primary Injector Harness: HT-186007

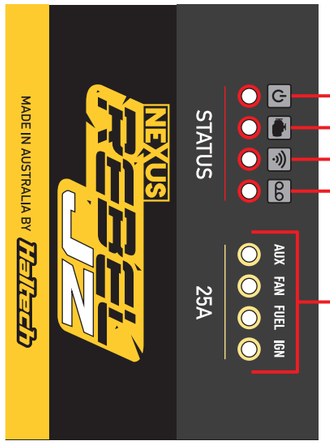


1 Power LED
2 DTC LED
3 Wireless LED
4 Datalog LED
5 25A HCO LEDs
6 Battery Negative Stud
7 Battery Positive Stud
8 Wi-Fi Antenna (RP-SMA)
9 Onboard MAP sensor (4 BAR)
10 USB-C Port (Comms)
11 Connector A (AMP 34 pin Keyway 1)
12 Connector C (AMP 34 pin Keyway 2)
13 Connector E (DTP 4 pin)
14 Mounting Holes








| LED | COLOR | CONDITION |
|---|---|---|
| Power | Green | Normal operation (on main power or low power mode) |
| | Blue | Connect to unit and install firmware |
| | Red | Hardware fault |
| DTC | None | DTCs not present |
| | Yellow | A DTC is present (of any kind, past/present/not severe/severe) |
| Wireless | None | Wireless is disabled |
| | Green solid | Wireless is enabled |
| | Green flashing | Wireless is enabled and connected to NSP |
| Datalog | None | Unit is not logging |
| | Yellow flashing | Unit is logging, unit is not looping or not full |
| | Yellow | Unit is logging, unit is looping or full |
| HCO (25A) | None | Channel is off |
| | Green | Channel is on - duty cycle is >0% and operating correctly |
| | Red | Channel is not allowed to be driven. Usually caused by (but not limited to) an over-current this drive cycle |

# REBEL JZ ECU SPECIFICATIONS





| FEATURES | |
|---|---|
| Drive-By-Wire Throttle Support | Single |
| Flex Fuel | YES |
| Closed Loop O2 Control | YES |
| Knock Control | YES |
| Long Term Learning | Up to 3D |
| Data Logging | Laptop + Onboard |
| Anti-Lag Rotational Idle | YES |
| Launch Control | YES |
| Traction Control | YES |
| Tuning Table Resolution | 32 x 32 |

| FEATURES continued | |
|---|---|
| CAN Network | 1 |
| Nitrous Control Stage | 6 |
| Boost Control | 3D Closed Loop |
| Cam Control (VVTi) | YES |
| Flat Shift Control | Advanced |
| Shock Travel & Ride Height | YES |
| Trans Brake | YES |
| Race Timer | YES |
| On-board Wideband | Single Channel LSU 4.9 |
| Engine Protection | Multi Level |



| OUTPUTS | |
|---|---|
| Ignition | 6 |
| Injector (High Impedance only) | 6 |
| Digital Pulsed Outputs (user definable) | 5 |
| Tachometer Output | 1 |
| Half Bridge Outputs (IAC or Drive-By-Wire Throttle) | 4 |
| CAN / Transmission Power Supply (8A) | 2 |
| Switched 12V (25A) | 1 |
| Fuel Pump Control (25A) | 1 |
| Fan Control (25A) | 1 |
| Starter HCO AX25+ (User definable) | 1 |

| INPUTS | |
|---|---|
| Differential Engine Position Inputs | 3 (Trigger, Home 1 and Home 2) |
| Coolant / Air Temperature Input | 2 |
| Fuel / Oil Pressure Input | 2 |
| Throttle Position / Pedal Position Input | 4 |
| Onboard MAP sensor (4 bar) | 1 |
| Analog Voltage Inputs (user definable) | 3 |
| Synchronised Pulsed Inputs (user definable) | 2 |
| Transmission / Vehicle Speed Sensor Inputs | 1 |
| Knock Sensor Inputs | 2 |
| On-board Wideband Controller (Bosch LSU 4.9 sensor only) | 1 |
| Flex Fuel Sensor Input | 1 |

| COMMUNICATIONS | |
|---|---|
| CAN Bus Network (Haltech CAN devices only) | 1 |
| High Speed USB 2.0 (USB-C interface) 480 Mbit/s connection | 1 |
| Power up over USB | Datalogging, settings and firmware upgrade available |
| Wireless | 900 kB/s datalog extraction. Hardware lockout for security |

| DATA LOGGING AND ANALYSIS | |
|---|---|
| Location | Onboard or PC logging |
| Onboard storage | 32MB |
| Maximum sampling frequency | 1kHz |
| Maximum channels per log | 300 |
| 4 Channel Oscilloscope | 50kSa/s per channel, 2ms/Div limit |

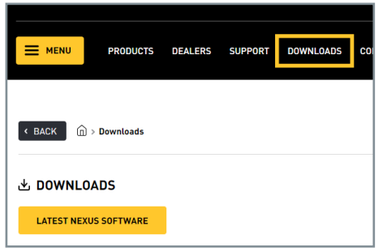
| DIMENSIONS | |
|---|---|
| Enclosure (Not including connector protrusion) | 196 x 130 x 44.5 mm (7.7 x 5.2 x 1.8 in) |
| Overall (Including connector protrusion) | 196 x 149 x 44.5 mm (7.7 x 5.9 x 1.8 in) |
| Weight | 1.15 kg (2.53 lbs) |
| Operating Temperature (ambient) | -40 to 85°C (-40 to 185°F) |
| 12 x Onboard Temperature Sensing Zones | ECU: -40 to 125°C (-40 to 255°F) |
| | PDM: -40 to 150°C (-40 to 302°F) |

| ELECTRICAL | |
|---|---|
| Power Supply (across power terminals) | 8 to 22V |
| No output static current draw | < 1A |
| Low Power Mode (USB) | 4 to 5.5V |
| Static current draw from USB port | < 500mA |

## Installing the NSP software

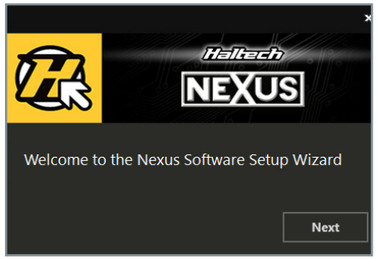
Haltech NSP (Nexus Software Programmer) is the software used for tuning and programming the Nexus Rebel JZ ECU. Follow these steps to install the Haltech NSP software:

**1. Download the NSP installer** - Go to the Haltech website (www.haltech.com), navigate to the 'Downloads' section, and click on the download link.




**2. Run the installer file** - Once the download is complete, locate the downloaded file (usually in the 'Downloads' folder of your computer) and double-click on the file to run the Nexus Software Setup Wizard.

**3. Launch Haltech NSP** - Once the installation is complete, you can launch the Haltech NSP software from the Windows 'Start' menu or using the desktop shortcut that was created.









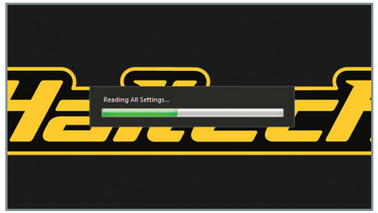



## Going online with the ECU

With the NSP software open, connect the supplied Haltech USB cable between your laptop and the USB-C port on the front of the Nexus Rebel JZ ECU.



The USB connection will let the NSP software automatically recognize the ECU and activate the unit in low power mode. This allows you to either upload a basemap or create a new one through the setup wizard before installing the ECU into the vehicle. In low power mode, the ECU's inputs and outputs are disabled, ensuring you to safely configure your vehicle setup prior to installing the unit and powering it up.




## Rebel JZ ECU Setup Wizard

The NSP software features a comprehensive setup wizard, designed to tailor the Rebel JZ ECU settings for specific Toyota JZ engine applications.

The process begins with naming your vehicle, which creates a dedicated folder on your laptop for saving maps and datalog files, and offers the option to add a vehicle description - a useful feature for quickly identifying different map versions.

Next, you select a base engine from a list of Toyota JZ engines, a step that determines engine capacity and compression ratio settings in the map, along with other engine-specific information.

In the next step, you define the camshaft profile being used, which influences map parameters like fueling, spark, idle control, and O2 control.

The air intake system setup follows, allowing you to choose between naturally aspirated or forced induction systems and between cable-operated or Drive-By-Wire throttles, with NSP software adjusting inputs and outputs accordingly.

The next step involves selecting the appropriate MAP sensor, with an onboard 4-bar sensor for naturally aspirated and boosted engines up to 43 psi, or the option for an external sensor.

In the last few steps you define the fuel and ignition system setup by selecting the specific fuel injectors, choose your fuel regulator setup and define the base fuel pressure. The wizard will also let you configure the ignition setup by selecting your ignition coils from a list.

After completing these steps, NSP provides a summary of your selections for confirmation, allowing any necessary adjustments before finalizing. This thorough setup ensures that the Nexus Rebel JZ ECU, coupled with a Rebel JZ terminated harness, is optimally configured to start and run the engine with a base tune.



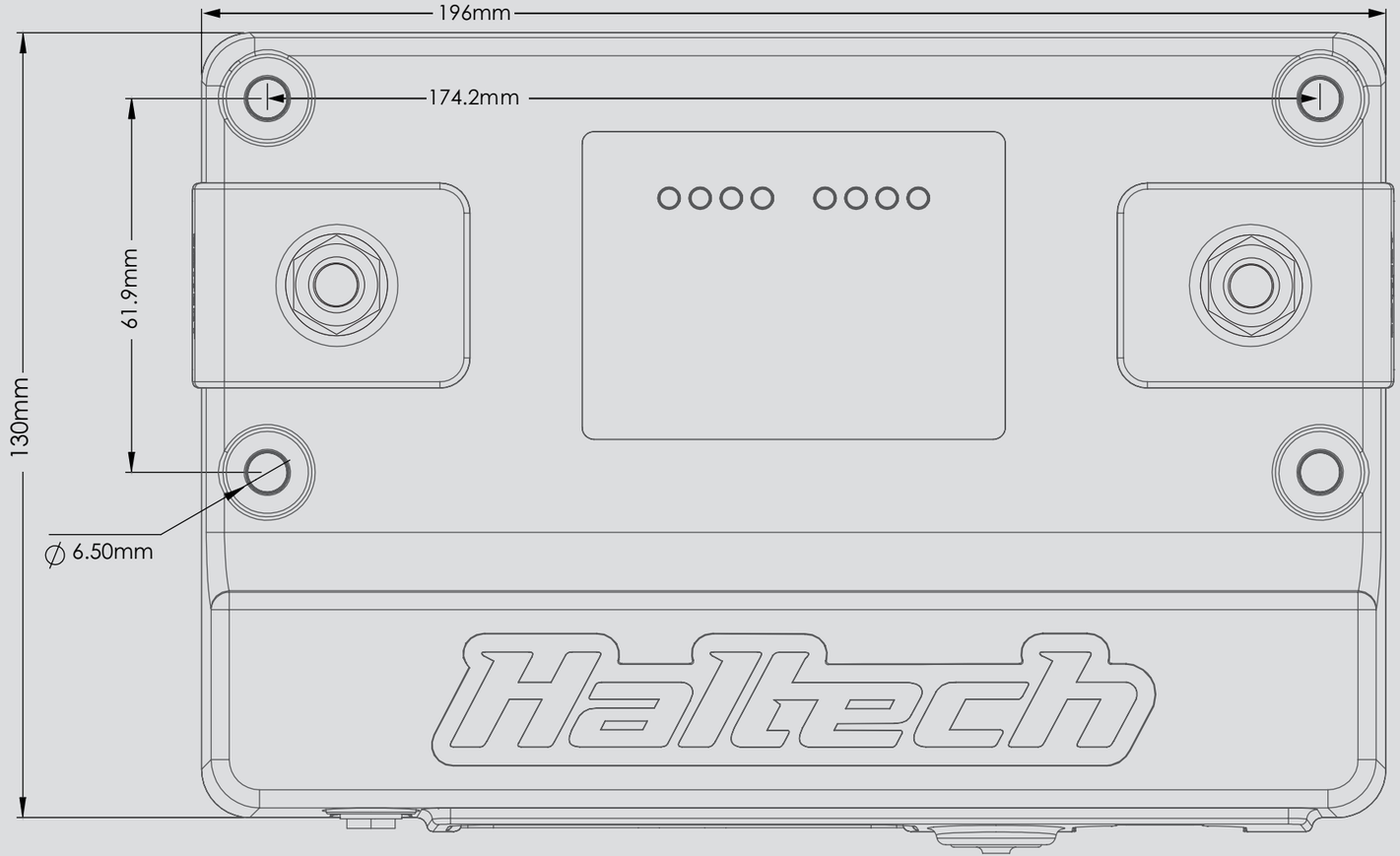

## Haltech Connect

The Haltech Connect App enables you to connect wirelessly to and interact with your Nexus Rebel JZ ECU via your smartphone or tablet. View real-time data from the ECU, setup basic gauges, clear DTC's, assign wiring, and adjust select parameters. Available for free on Google Play (Android) and the Apple Apps Store (IOS).

GET IT ON Google Play

Download on the App Store

MOUNTING TEMPLATE



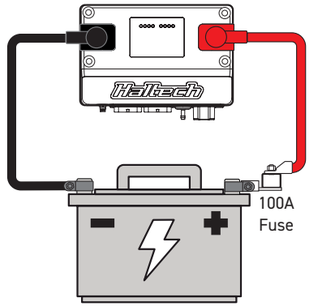

MOUNTING TEMPLATE

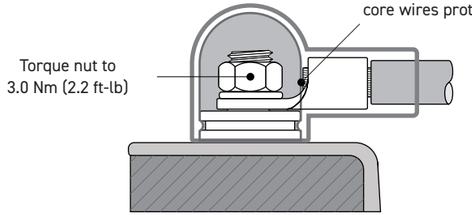
## Battery Positive and Negative

For correct operation, the battery positive and battery negative must be connected to the Nexus Rebel JZ ECU at all times.

The Nexus Rebel JZ ECU's positive (red) terminal must be connected to the positive (+) terminal of the battery. It is recommended to use a 100A fuse (sample CF fuse shown below) in this connection. Use the supplied ring terminal and red boot, along with a red 4 AWG battery cable (sold separately), to complete the connection.

The Nexus Rebel JZ ECU's negative (black) terminal must be connected to the negative (–) terminal of the battery using the supplied ring terminal and black boot, along with a black 4 AWG battery cable (sold separately), to complete the connection.




Rebel JZ ECU Battery Connection

## Nexus Rebel JZ Terminated Harness

The Nexus Rebel JZ ECU directly integrates with a Nexus Rebel JZ terminated harness, compatible with supported Toyota JZ engines through the use of application-specific adapters and sub-harnesses.

The harness features terminated connections for both the engine bay and cabin, including:

- Nexus Rebel JZ ECU connectors
- Crank and cam sensors
- Oil and fuel pressure sensors
- Coolant and intake air temperature sensors
- Throttle and pedal connectors
- Knock sensors
- Bosch LSU 4.9 wideband lambda sensor
- Ignition switch input and alternator control
- 6x injector and 6x ignition outputs
- Thermofan and fuel pump control
- Transmission wiring
- Spare inputs and outputs
- Haltech CAN devices

More information about these connections is explained in the quick start guide included with the harness package.





DBW Throttle Sub-harness



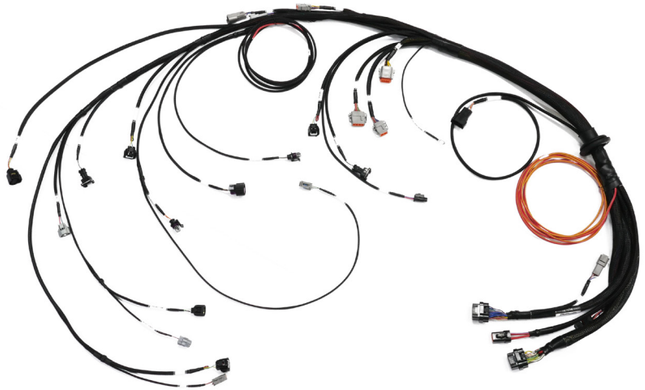
Ignition harness



Throttle adapters



Rebel JZ main harness



Alternator adapters



Injector harnesses

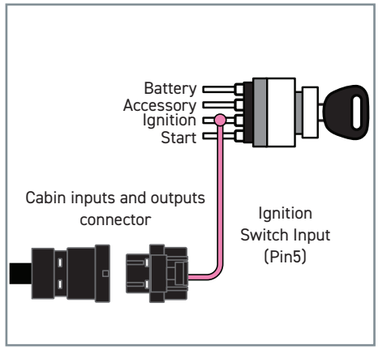


## Ignition Switch Input

The ignition switch input (PIN 5 on Cabin Connector) must be connected to a switched +12V source to turn the Nexus Rebel JZ ECU on.

When connecting this pin to the ignition key switch, it is important to make sure to use the main ignition wire (i.e., not accessory) so it doesn't lose power when the key is in the "Start" position, causing the ECU to momentarily turn off.

The pink wire is the flying lead (unbraided) coming out of the in-cabin inputs and outputs connector branch on the Rebel JZ terminated harness.




## User Definable Inputs and Outputs

Most of the inputs and outputs (I/O) on the Nexus Rebel JZ ECU are preset to match the Rebel JZ terminated harness. This significantly reduces the number of wire assignments that need configuration in the NSP software.

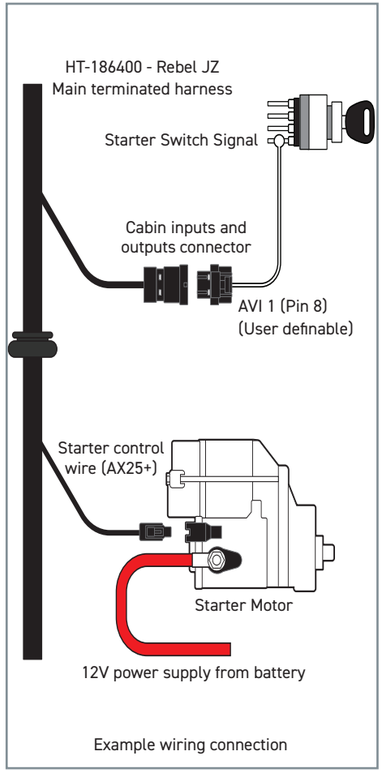
However, some I/Os are user definable, providing the right level of flexibility to meet specific needs in your application. The following section briefly explains the use of these I/Os and gives examples of typical applications.

**Auxiliary High Current Output (AX25+)**

The Nexus Rebel JZ ECU provides a user-definable high-current output, capable of supplying +12V with a maximum rating of 25A. This output is connected via the Red/Blue 12AWG cable on the Rebel JZ terminated harness, labeled as STARTER.

The Rebel JZ terminated harness is primarily configured for the auxiliary high current output (AX25+) to be utilized in controlling the starter. However this auxiliary high current output can be designated to be used for other auxiliary devices.

Using the Nexus Software Programmer, you can customize this output's function to control various devices.




Example wiring connection

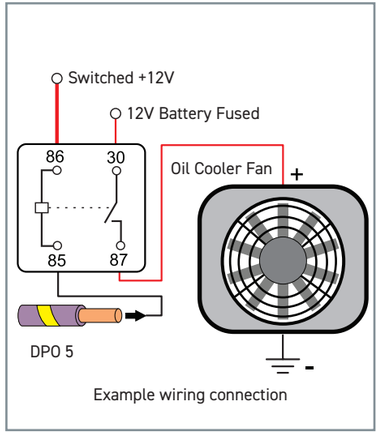


**Digital Pulsed Outputs (DPO)**

Number of user definable channels: 5

Digital Pulsed Outputs (DPOs) are capable of generating pulsed waveforms with varying duty cycles, varying frequencies, or switched states (On or Off). When activated by the ECU, a DPO output switches to ground.

DPOs can be used to control various low-current devices (up to 3A max), such as, solenoids or warning lights. Additionally, DPOs can be used to switch relays to drive other high-current devices.



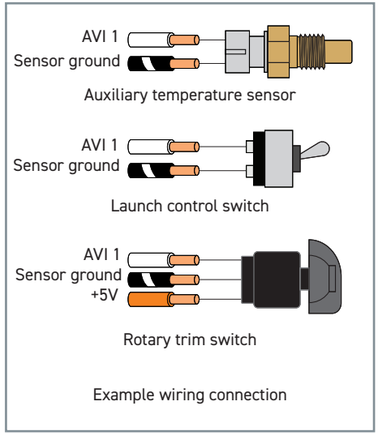

Example wiring connection

**Analog Voltage Inputs (AVI)**

Number of user definable channels: 3

Analog Voltage Inputs (AVIs) are inputs that accept variable voltage signals ranging from 0-5V, typical of pressure, temperature, and position sensors. These inputs can also accommodate switches that alternate between two distinct voltage levels.

AVIs feature a software-selectable 1K-ohm pull-up resistor to 5V, which is typically enabled for temperature-related sensors and switched to ground inputs. They are usually disabled for sensors with an external +5V supply, such as trim switches or linear position sensors.



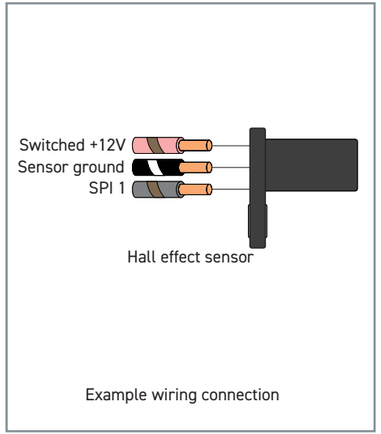

Example wiring connection

**Synchronized Pulsed Inputs (SPI)**

Number of user definable channels: 2

Synchronized Pulsed Inputs are capable of measuring the duty cycle or frequency of a signal, in addition to analog voltages like AVIs. These inputs are suitable for various sensors, including wheel speed sensors with a software-selectable 1K-ohm pull-up resistor to 5V, if the sensor requires.

SPIs are compatible with both digital (hall effect or optical) and analog (reluctor) sensors. They have a maximum input voltage rating of 25V and can measure frequencies up to a maximum of 22.5kHz.



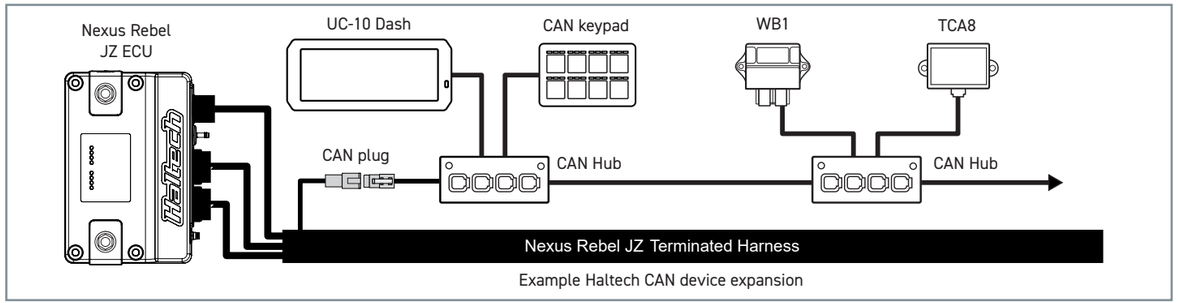

Example wiring connection

## Haltech CAN System

The Nexus Rebel JZ ECU features a CAN channel that facilitates communication with a range of Haltech CAN expansion devices, available for separate purchase. This integration capability enhances the functionality and versatility of the ECU, allowing for a more comprehensive and customized vehicle control system.

The range of compatible Haltech CAN expansion devices includes display dashes, keypads, power distribution modules, external wideband controllers, I/O expanders, thermocouple amplifiers, and CAN hubs.




Example Haltech CAN device expansion



## Setting up Wi-Fi communications

Wi-Fi communication is another method for connecting the Nexus Rebel JZ ECU to your laptop, serving as an alternative to a USB connection once the Wi-Fi module is enabled.

To set up your Wi-Fi connection follow these steps:

**1.** Open NSP and connect your Nexus Rebel JZ ECU using the provided USB-C cable.

**2.** Click on 'Connections' in the navigation tree and enable the Wi-Fi module.

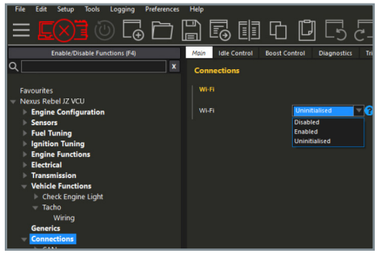
**3.** Under 'Connections', select 'Wi-Fi' to set up your SSID and password. Note that your SSID must be at least 1 character long, and your password at least 8 characters.

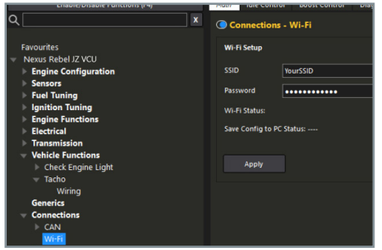
**4.** Click 'Apply'.

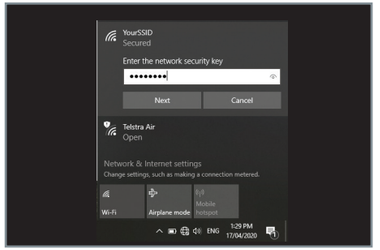
**5.** Power up the ECU using main power (ignition switch on), then go to your computer's Network settings. Connect to your Nexus Rebel JZ ECU by selecting your chosen SSID and entering your password.

NOTE: The ECU must be powered by main power for Wi-Fi communication. Up to two computers can connect to the ECU via Wi-Fi, and one via USB-C, at any given time. When the module is disabled, it is completely inactive and held in an OFF state.





## ENGINE START UP GUIDE

Starting your Toyota JZ engine with a Nexus Rebel JZ ECU and terminated harness involves several steps. Please note that this is a general overview, and the exact procedure may vary based on your specific application. Here are the basic steps:

**1. Preparation** - Ensure that the Rebel JZ ECU is properly installed and securely mounted in your vehicle. Confirm all necessary wiring connections are made as per the Nexus Rebel JZ terminated harness documentation and your engine's specific requirements.

**2. Power and Ground** - Use a sufficiently charged car battery, connected to the Rebel JZ ECU as outlined in this quick start guide. The Rebel JZ terminated harness does not provide grounding for your engine. Ensure your engine is properly grounded with a grounding strap connecting it to the battery.

**3. Sensors and Inputs** - Check that all required sensors (e.g., crank and cam sensors, MAP sensor, coolant and air temperature sensors, throttle position sensor, etc.) are correctly connected to the harness and that sensor values read accurately in the NSP software.

**4. Outputs** - Make correct connections for required outputs to engine components such as injectors, ignition coils, thermofan, and fuel pump.

**5. Configure the Nexus Rebel JZ ECU settings** - Use the setup wizard in the NSP software to configure ECU settings, specifying engine type, injector size, ignition settings, and other parameters specific to your setup.

**6. Safety Checks** - Double-check all connections for issues like wiring shorts or loose connections that could pose a hazard. Verify that fuel pressure is within the expected range and there are no fuel leaks. Power cycle the ECU to prime the fuel pump and pressurize the fuel system.

**7. Pre Start up** - Briefly crank the engine to ensure it turns over smoothly and without any unusual sounds or issues. Once confident in the setup, start the engine using the ignition key or start button.

**8. Monitor and Adjust** - After the engine starts and idles, monitor data such as coolant temperature and wideband O2, and listen for any abnormal sounds. While the Nexus Rebel JZ ECU will run the engine using a pre-configured base map, further tuning is needed for optimal performance, fuel economy, and emissions. Conduct thorough testing under various conditions.

Remember that engine tuning and setup can be complex and require expertise. If you are not experienced with EFI (Electronic Fuel Injection) systems and engine management, seeking assistance from a professional tuner is recommended for safe and reliable engine operation.

For any questions or technical support regarding this product, you can contact Haltech using the contact details at the end of this guide. Alternatively, scan the QR code below to access the Haltech Knowledge Base and technical support page.



# WARRANTY CERTIFICATE

*At Haltech we make every effort to design and manufacture fault-free products that perform up to or above the market expectations. All our products are covered by a Limited 12 Month Warranty.*

### Haltech Limited Warranty

Unless specified otherwise, Haltech warrants its products to be free from defects in material or workmanship for a period of 12 months from the date of purchase.

If the Haltech product is found to be defective as mentioned above, it will be replaced or repaired if returned prepaid along with proof of purchase. Proof of purchase in the form of a copy of the original purchase invoice, receipt or bill of sale which indicates that the product is within the warranty period, must be presented to obtain warranty service.

Replacement or repair of a defective product shall constitute the sole liability of Haltech. To the extent permitted by law, the foregoing is exclusive and in lieu of all other warranties or representations, either expressed or implied, including any implied warranty of merchantability or fitness. In no event shall Haltech, be liable for special or consequential damages.

### Product Returns

Please include a copy of the original purchase invoice, receipt or bill of sale along with the unused, undamaged product and its original packaging. Any product returned with missing accessory items or packaging will incur extra charges to return the item to a re-saleable condition.

All product returns must be sent via a freight method with adequate tracking, insurance and proof of delivery services. Haltech will not be held responsible for product returns lost during transit.

### Returns of Products Supplied in Sealed Packaging

The sale of any sensor or accessory supplied in sealed packaging is strictly non-refundable if the sealed packaging has been opened or tampered with. This will be clearly noted on the product packaging. If you do not accept these terms please return the sensor in its original unopened packaging within 30 days for a full refund.

A sensor or accessory product may be returned after 30 days of purchase (with its sealed packaging intact) for credit only (no refunds given) and will be subject to a 10% restocking fee.

### Installation of Haltech Products

No responsibility whatsoever is accepted by Haltech for the fitment of Haltech Products. The onus is clearly on the installer to ensure that both their knowledge and the parts selected are correct for that particular application. Any damage to parts or consequential damage or costs resulting from the incorrect installation of Haltech products are totally the responsibility of the installer.

Always disconnect the battery when doing electrical work on your vehicle. Avoid sparks, open flames or use of electrical devices near flammable substances. Do not run the engine with a battery charger connected as this could damage the ECU and other electrical equipment.

Do not overcharge the battery or reverse the polarity of the battery or any charging unit. Disconnect the Haltech ECU from the electrical system whenever doing any welding on the vehicle by unplugging the wiring harness connector from the ECU.

After completing the ECU installation, make sure there is no wiring left un-insulated. Uninsulated wiring can cause sparks, short circuits and in some cases fire. Before attempting to run the engine ensure there are no leaks in the fuel system.

All fuel system components and wiring should be mounted away from heat sources, shielded if necessary and well ventilated. Always ensure that you follow workshop safety procedures. If you're working underneath a jacked-up car, always use safety stands!

### Haltech Off-Road Usage Policy

In many states it is unlawful to tamper with your vehicle's emissions equipment. Haltech products are designed and sold for sanctioned off-road/competition non-emissions controlled vehicles only and may never be used on a public road or highway.

Using Haltech products for street/road use on public roads or highways is prohibited by law unless a specific regulatory exemption exists (more information can be found on the SEMA Action Network website www.semasan.com/emissions for state by state details in the USA).

It is the responsibility of the installer and/or user of this product to ensure compliance with all applicable local and federal laws and regulations. Please check with your local vehicle authority before purchasing, using or installing any Haltech product.

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